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Object/target tracking refers to the problem of using sensor measurements to determine the location, path and characteristics of objects of interest. A sensor can be any measuring device,

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such as radar, sonar, lidar, camera, infrared sensor, microphone, ultrasound or any other sensor that can be used to collect information about objects in the environment.

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Object tracking is the process of: Taking an initial set of object detections (such as an input set of bounding box

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coordinates) Creating a unique ID for each of the initial detections And then tracking each of the objects as they move around frames in a video, maintaining the assignment of unique IDs

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To capture the data, the researchers

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designed an automated system consisting of an industrial robotic arm with precise control, a 3D motion-tracking system, depth and traditional cameras, and software that stitches everything together. The arm pushes around modular objects that can be adjusted for weight, shape, and mass distribution.

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